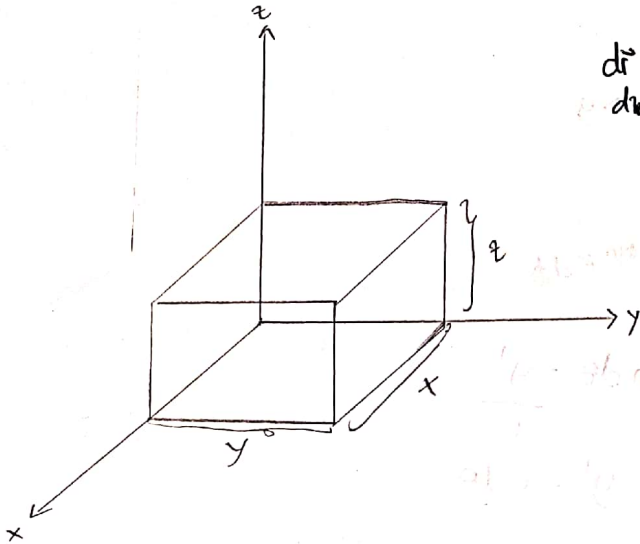


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1) Koordinat Cartesius (x,y,z)



$$d\vec{r} = \hat{i}dx + \hat{j}dy + \hat{k}dz$$

$$dv = dx dy dz$$

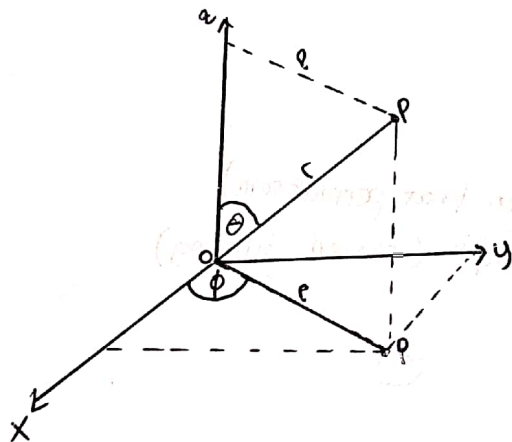
$$\sim \text{gradien} = \nabla t = \hat{i} \frac{\partial t}{\partial x} + \hat{j} \frac{\partial t}{\partial y} + \hat{k} \frac{\partial t}{\partial z}$$

$$\sim \text{Divergen} = \nabla \cdot \vec{V} = \frac{\partial V_x}{\partial x} + \frac{\partial V_y}{\partial y} + \frac{\partial V_z}{\partial z}$$

$$\sim \text{Rotasi} = \Delta \times \vec{V} = \hat{i} \left(\frac{\partial V_z}{\partial y} - \frac{\partial V_y}{\partial z} \right) + \hat{j} \left(\frac{\partial V_x}{\partial z} - \frac{\partial V_z}{\partial x} \right) + \hat{k} \left(\frac{\partial V_y}{\partial x} - \frac{\partial V_x}{\partial y} \right)$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ V_x & V_y & V_z \end{vmatrix}$$

2) Sistem koordinat bola (r, ϕ, θ)



Persamaan koordinat bola

$$x = r \sin \theta \cos \phi$$

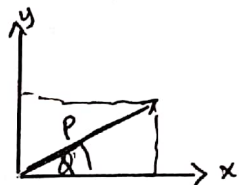
$$\rightarrow x = r \sin \theta \cos \phi$$

$$y = r \sin \theta \sin \phi$$

$$\rightarrow y = r \sin \theta \sin \phi$$

$$z = r \cos \theta$$

Analisis xy → bidang xy

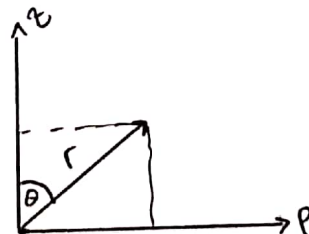


$$\sin \phi = \frac{y}{\rho}, y = \rho \sin \phi$$

$$x = \rho \cos \phi$$

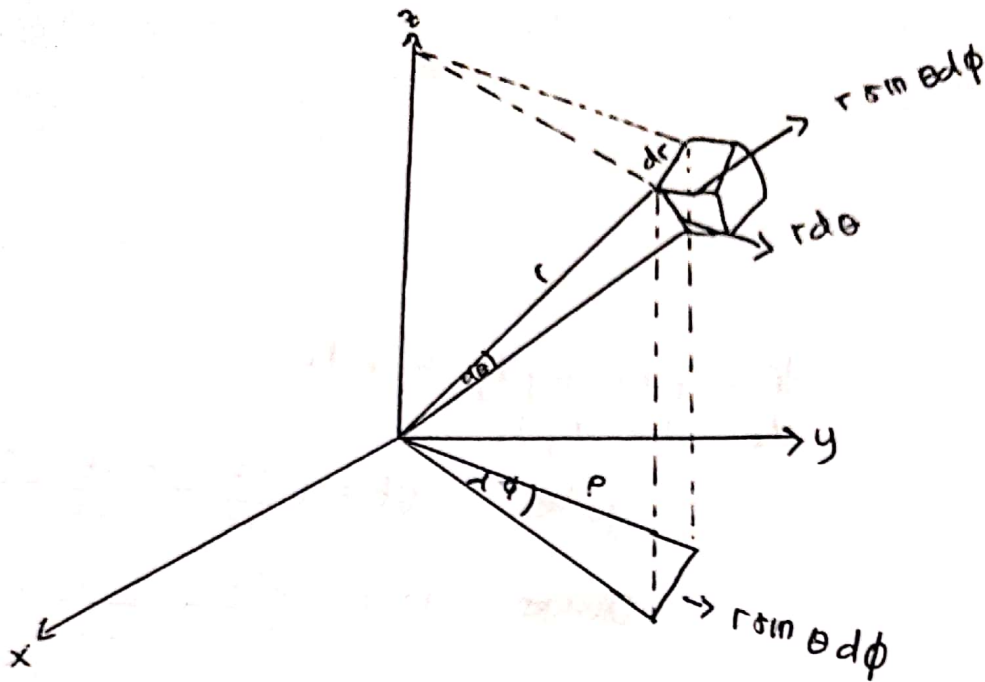
$$z = z$$

analisis zρ bidang zρ



$$z = r \cos \theta$$

$$\rho = r \sin \theta$$



$$r \sin \theta d\phi = \frac{x'}{\rho}$$

$$d\phi = \frac{x'}{r \sin \theta}$$

$$x' = r \sin \theta d\phi$$

$$\sin \theta d\theta = \frac{y'}{r}$$

$$y' = r d\theta$$

maka, $dv = dr \cdot r d\theta \cdot r \sin \theta d\phi$

$$dv = r^2 dr \sin \theta d\theta d\phi \text{ (elemen volume)}$$

$$\Rightarrow dv = r^2 \sin \theta dr d\theta d\phi$$

$$d\Delta = r d\theta r \sin \theta d\phi$$

$$\Rightarrow d\Delta = r^2 \sin \theta d\theta d\phi \text{ (elemen luas permukaan)}$$

$$\Rightarrow de^2 = dr^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \text{ (elemen panjang)}$$