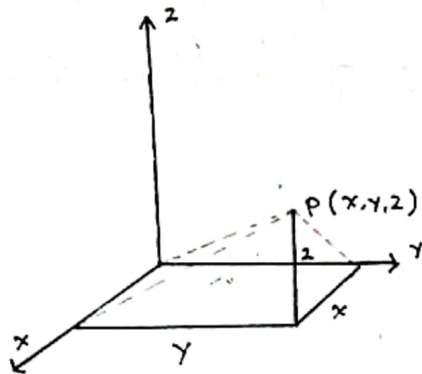


Nama : Dian Permata Hati
NPM : 2013022036 .

Gambar sistem koordinat Cartesius, koordinat silinder, dan koordinat bola .

* Koordinat Cartesius (x, y, z)



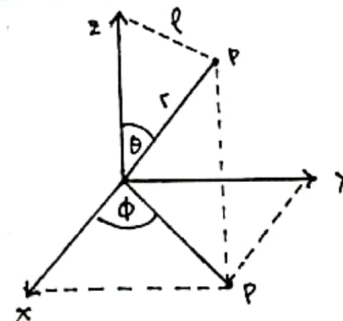
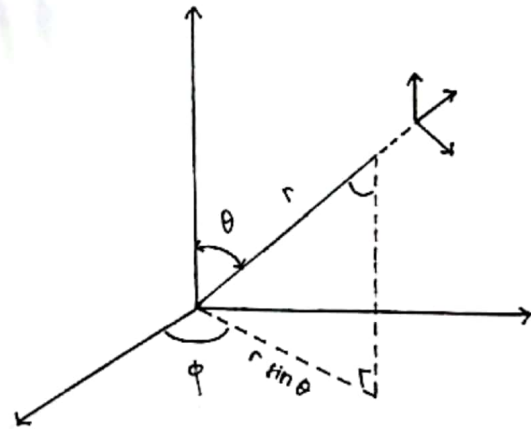
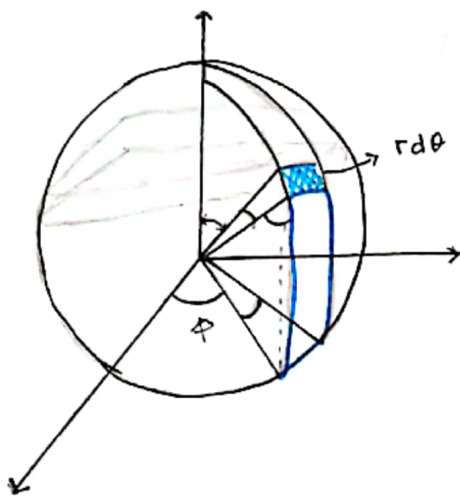
$$\text{- Gradien : } \nabla t = i \frac{\partial t}{\partial x} + j \frac{\partial t}{\partial y} + k \frac{\partial t}{\partial z}$$

$$\text{- Divergensi : } \nabla \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

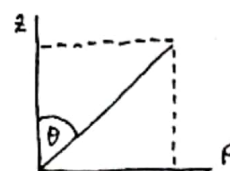
$$\text{- Rotasi : } \nabla \times \vec{v} = \hat{i} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{j} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{k} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

* Koordinat Bola (r, θ , ϕ)



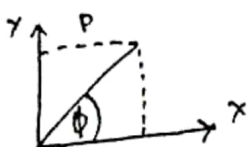
* Analisis Z P



$$z = r \cos \theta$$

$$p = r \sin \theta$$

* Analisis xy

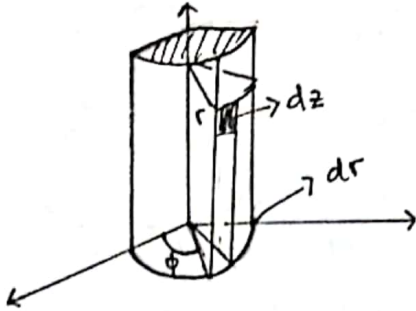


$$\sin \phi = \frac{y}{p}, \quad y = p \sin \phi$$

$$x = p \cos \phi$$

- Gradien $= \nabla t = \hat{r} \frac{\partial t}{\partial r} + \hat{\theta} \left(\frac{1}{r} \frac{\partial t}{\partial \theta} \right) + \hat{\phi} \left(\frac{1}{r \sin \theta} \frac{\partial t}{\partial \phi} \right)$
- Divergensi : $\nabla \cdot \vec{v} = \frac{1}{r^2} \left(\frac{\partial}{\partial r} r^2 v_r \right) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (v_\theta \sin \theta) + \frac{1}{r \sin \theta}$

Koordinat silinder



- Gradienn: $\nabla t = \hat{r} \left(\frac{\partial t}{\partial r} \right) + \hat{\phi} \left(\frac{1}{r} \frac{\partial t}{\partial \phi} \right) + \hat{z} \left(\frac{\partial t}{\partial z} \right)$
- Divergensi : $\nabla \cdot \vec{v} = \frac{1}{r} \left(\frac{\partial}{\partial r} \right) (r v_r) + \frac{1}{r} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$