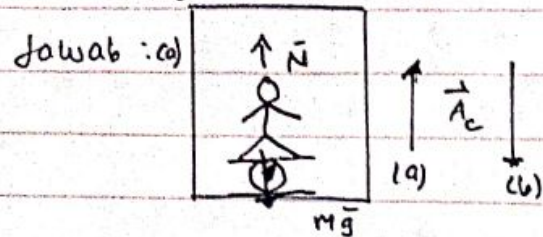


S.1 A 120-lb person stand on a bathroom spring scale while riding in an elevator. If the elevator for has (a) upward and (b) downward acceleration of $g/4$, what is the weight indicated on the scale in each case?



$$\vec{N} + m\vec{g} - m\vec{A}_0 = 0$$

$$N - mg - m\frac{g}{4} = N - mg - m\frac{g}{4} = N - \frac{5}{4}mg = 0$$

$$W' = N = \frac{5}{4}mg = \frac{5}{4}W$$

$$W' = 150 \text{ lb}$$

(b) $N - mg + m\left(\frac{g}{4}\right) = 0$ $W' = W - \frac{W}{4} = \frac{3}{4}W$

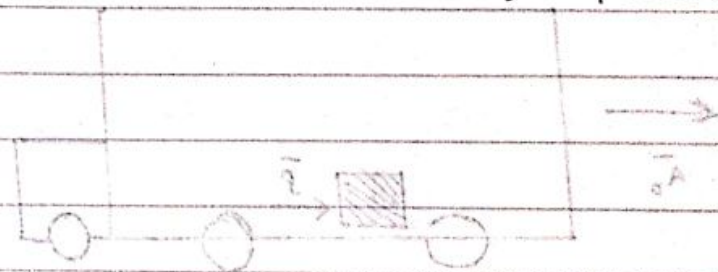
S.2 An ultracentrifuge has a rotational speed of 500 rps. (a) Find the centrifugal force on a 1- μ g particle in the sample chamber if the particle is 5 cm from the rotational axis. (b) Express the result as the ratio of the centrifugal force to the weight of the particle.

Jawab : (a) $\vec{F}_{\text{cent}} = -m\vec{\omega} \times (\vec{\omega} \times \vec{r})$

untuk $\vec{\omega} \perp \vec{r} \Rightarrow \vec{F}_{\text{cent}} = m\omega^2 r' \hat{e}_r$

$$\omega = 500 \text{ s}^{-1} = 1000\pi \text{ s}^{-1}$$

$$F_{\text{cent}} = 10^{-6} \times (1000\pi)^2 \times 5 \hat{e}_r = 5\pi^2$$



(b) $\frac{F_{\text{cent}}}{F_g} = \frac{m\omega^2 r'}{mg} = \frac{(1000\pi)^2 \times 5}{980} = 0,04 \times 10^9$

5.3 A plumb line is held steady while being carried along in a moving train. If the mass of the plumb bob is m , find the tension in the cord and the deflection from the local vertical if the train is accelerating forward with constant acceleration $g/10$. (Ignore any effects of earth's rotation)



$$m\vec{a} + T - m\vec{A} = 0$$

$$-mg\hat{j} + T\cos\theta\hat{j} + T\sin\theta\hat{i} - m\left(\frac{g}{10}\right)\hat{i} = 0$$

$$T\cos\theta = mg,$$

$$T\sin\theta = \frac{mg}{10}$$

$$\tan\theta = \frac{1}{10}, \quad \theta = 5.71^\circ$$

$$T = \frac{mg}{\cos\theta} = 1.005 mg$$

5.4 If in problem 5.3, the pivot line is not held steady but oscillates as a simple pendulum, find the period of oscillation for small amplitude.

$$\Rightarrow \vec{a} = \vec{a} - \vec{A}_0 = g\vec{j} - \frac{g}{10}\vec{i}$$

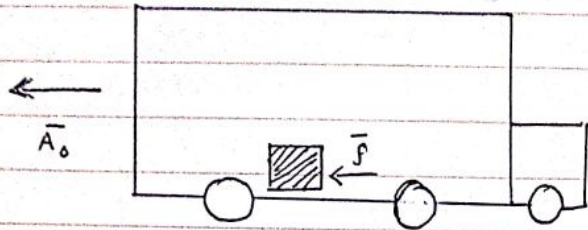
Untuk osilasi kecil pada pendulum sederhana:

$$T = 2\pi \sqrt{\frac{l}{g'}}$$

$$g' = \sqrt{g^2 + \left(\frac{g}{10}\right)^2} = 1.005 g$$

$$T = 2\pi \sqrt{\frac{l}{1.005 g}} = 1.995 \pi \sqrt{\frac{l}{g}}$$

5.5. A hauling truck is traveling on a level road. The driver suddenly applies the brakes, causing the truck to decelerate by a amount $g/2$. This causes a box in the rear of the truck to slide forward. If the coefficient of sliding friction between the box relative to (a) the truck and (b) the road,



lok, lalu

$$\vec{f} - m\vec{A}_0 = m\vec{a}$$

sekarang, f adalah ~~resist~~ ~~force~~ ~~force~~, maka

(b) $a = \frac{f}{m} = -\frac{Nmg}{m} = -Ng = -\frac{g}{2}$

At $a = -\frac{g}{2}$ from above, $m\vec{a} - m\vec{A}_0 = m\vec{a}$ maka
 (a) $a' = a - A_0 = -\frac{g}{2} + \frac{g}{2} = 0$

5.6. The position of a particle in a fixed inertial frame of reference is given by the vector

$$\vec{r} = i(x_0 + R \cos \Omega t) + j R \sin \Omega t$$

where x_0 , R , and Ω are constants

- (a) Show that the particle moves in a circle with constant speed
 (b) Find two coupled, first-order differential equations of motion that relate the components of position, x' and y' , and the components of velocity, $\dot{x}'$ and $\dot{y}'$, of the particle relative to a frame of reference rotating with an angular velocity



$$\omega > k\omega$$

(c) Letting to fixed and rotating frames of reference coincide at times $t=0$ and letting $u' = x' + iy'$, find $u(t)$ assuming that $\Omega \neq -\omega$

Jawab: (a) $\vec{r} = \hat{i}(x_0 + R \cos \Omega t) + \hat{j}R \sin \Omega t$

$$\dot{\vec{r}} = -\hat{i}\Omega R \sin \Omega t + \hat{j}\Omega R \cos \Omega t$$

$$\dot{\vec{r}} \cdot \dot{\vec{r}} = v^2 = \Omega^2 R^2 \quad \Rightarrow \quad v = \Omega R$$

(b) $\vec{r} = \vec{r} - \vec{\omega} \times \vec{r}$ ketika $\vec{r} = \hat{i}x' + \hat{j}y'$

$$= -\hat{i}\Omega R \sin \Omega t + \hat{j}\Omega R \cos \Omega t - \omega \hat{k} \times (\hat{i}x' + \hat{j}y')$$

$$= -\hat{i}\Omega R \sin \Omega t + \hat{j}\Omega R \cos \Omega t - \hat{j}\omega x' + \hat{i}\omega y'$$

$$\dot{x}' = \omega y' - \Omega R \sin \Omega t$$

$$\dot{y}' = -\omega x' + \Omega R \cos \Omega t$$

(c) let $u' = x' + iy'$ $= i - \sqrt{-1}$

$$\dot{u}' = \dot{x}' + i\dot{y}' = \omega y' - \Omega R \sin \Omega t - i\omega x' + i\Omega R \cos \Omega t$$

$$i\omega u' = -\omega y' + i\omega x'$$

$$\rightarrow \dot{u}' + i\omega u' = -\Omega R \sin \Omega t + i\Omega R \cos \Omega t = i\Omega R e^{i\Omega t}$$

$$u' = A e^{-i\omega t} + B e^{i\Omega t}$$

$$\dot{u}' = -i\omega A e^{-i\omega t} + i\Omega B e^{i\Omega t}$$

$$+ i\omega u' = i\omega A e^{-i\omega t} + i\omega B e^{i\Omega t}$$

$$\rightarrow \dot{u}' + i\omega u' = i(\omega + \Omega) B e^{i\Omega t} \quad \text{Maka } B = \frac{\Omega R}{\omega + \Omega}$$

$$u' = A + B = x'(0) + iy'(0) = x_0 + R$$

$$\rightarrow A = x_0 + R - B = x_0 + R - \frac{\Omega R}{\omega + \Omega} \quad \text{Maka } A = x_0 + \frac{\omega R}{\omega + \Omega}$$

$$u' = \left[x_0 + \frac{\omega R}{\omega + \Omega} \right] e^{-i\omega t} + \frac{\Omega R}{\omega + \Omega} e^{i\Omega t}$$