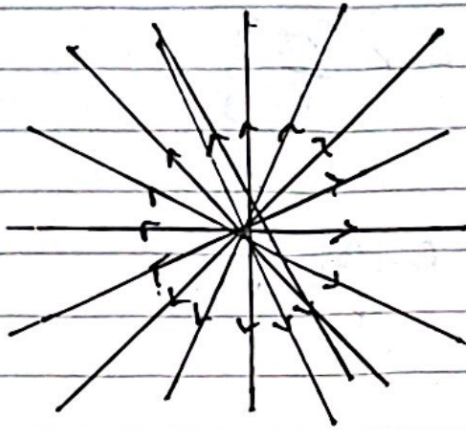


KALISMA

Usaha dan Energi



$$\begin{aligned}
 W &= \int_A^B \vec{F} \cdot d\vec{l} \\
 &= -q \int \vec{E} \cdot d\vec{l} \rightarrow dr \\
 &= -q \left[\int \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} dr \right]
 \end{aligned}$$

$$\begin{aligned}
 W &= -q \left[-\frac{q}{4\pi\epsilon_0 r} \right] \\
 &= q [V]
 \end{aligned}$$



$$W_1 = q_{n1} V_1 = 0$$

$$W_2 = q_{n2} V_2 = q \left[k \frac{q_1}{r} \right]$$

$$W_2 = q_{n2} V_2$$

$$W_3 = q_{n3} V_3$$

$$= q_{n3} \left[k \frac{q_1}{r_1} + k \frac{q_2}{r_2} \right]$$

$$= n_3 \left[\right.$$

$$W_4 = n_4 V_4 = n_4 \left[k \frac{n_1}{r} + k \frac{n_2}{\sqrt{2}r} + k \frac{n_3}{r} \right]$$

$$W_b = W_1 + W_2 + W_3 + W_4$$

$$= k \frac{n_1 n_2}{r} + k \frac{n_1 n_3}{r} + k \frac{n_2 n_3}{r} + \dots$$

$$W = \frac{1}{2} \sum_{i=1}^N \sum_{j \neq i}^N \frac{n_i n_j}{r_{ij}}$$

Dari semua persamaan tersebut dapat disimpulkan bahwa:

$$W = \frac{1}{2} \sum_{i=1}^N n_i V_i$$

$$W = \frac{1}{2} \sum_{i=1}^N n_i V_i$$

$$W = \frac{1}{2} \int \sigma V dp$$

$$W = \frac{1}{2} \int \sigma V ds$$

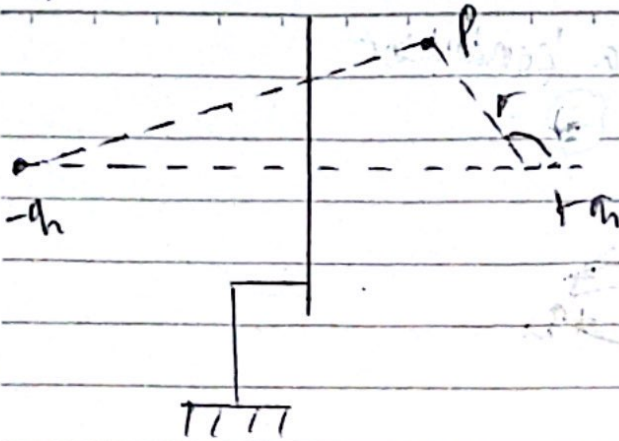
$$W = \frac{1}{2} \int \rho V d\tau$$

$$\rho = \epsilon_0 (\nabla \cdot \vec{E}) \text{ pers-gauss dlm bentuk diferensial}$$

$$\vec{E} = \frac{\rho}{\epsilon_0}$$

$$W = \frac{\epsilon_0}{2} \int \vec{E} \cdot d\vec{r}$$

KALISMA BAB 3 Metode Penentuan Potensial



1. Muatan listrik dan batang konduktor

$$V = \frac{1}{4\pi\epsilon_0} \frac{q}{r} + \frac{-q}{4\pi\epsilon_0 r'}$$

$$= \frac{q}{4\pi\epsilon_0} \left[\frac{1}{r} - \frac{1}{r'} \right]$$

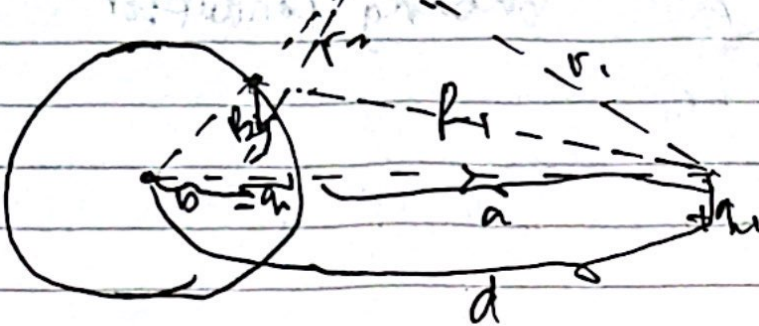
$$r' = (r^2 + 4h^2 + 4hr \cos \theta)^{\frac{1}{2}}$$

$$\vec{E}_r = k \left[\frac{1}{r^2} - \frac{1}{(r^2 + 4h^2 + 4hr \cos \theta)^{\frac{3}{2}}} \right]$$

$$\frac{\partial V}{\partial r} = k \left[\frac{1}{r^2} - \frac{1}{(r^2 + 4h^2 + 4hr \cos \theta)^{\frac{3}{2}}} \right]$$

$$= k \left[\frac{1}{r^2} - \frac{\frac{1}{2}(\dots)^{-\frac{1}{2}} [2r + 4h \cos \theta]}{(r^2 + 4h^2 + 4hr \cos \theta)^{\frac{3}{2}}} \right]$$

2. Muatan listrik dengan bola konduktor



$$V = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{R_1} - \frac{q_2}{R_2} \right) = 0$$

$$R_1^2 = a^2 + d^2 - 2ad \cos \theta$$

$$R_2^2 = a^2 + b^2 - 2ba \cos \theta$$

Untuk $V = 0$ maka :

$$\frac{q_1}{R_1} = \frac{q_2}{R_2} \Rightarrow \frac{q_1^2}{R_1^2} = \frac{R_2^2}{R_2^2} = \frac{a^2 + d^2 - 2ad \cos \theta}{a^2 + b^2 - 2ab \cos \theta}$$

$$\left(\frac{q_1}{q_2} \right)^2 = \left(\frac{R_1}{R_2} \right)^2 = \frac{d}{b} \left(\frac{a^2/d + a - 2a \cos \theta}{a^2/b + b - 2a \cos \theta} \right)$$