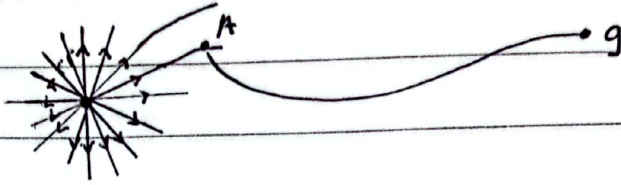


Usaha dan Energi



kenapa kenapa Q . karena harus menetralkan

$$W = \int_A^B \vec{F} \cdot d\vec{l}$$

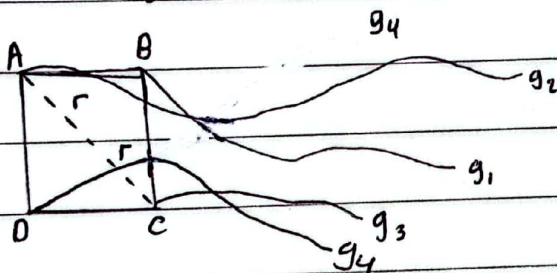
$$= -q \int \vec{E} \cdot d\vec{l}$$

$$= -q \left[\int \frac{1}{4\pi\epsilon_0} \frac{q}{r^2} dr \right]$$

$$W = -q \left[-\frac{q}{4\pi\epsilon_0 r} \right]$$

$$= q[V]$$

$$W = qV$$



$$W_1 = q_1 V_1 = 0$$

$$W_2 = q_2 V_2 = q_2 \left[k \frac{q_1}{r_1} \right]$$

$$W_2 = q_2 V_2$$

$$W_4 = q_4 V_4 = q_4 \left[k \frac{q_1}{r} + k \frac{q_2}{\sqrt{2}P} + k \frac{q_3}{P} \right] = q_4 \left[\dots \right]$$

$$W_3 = q_3 V_3$$

$$= q_3 \left[k \frac{q_1}{P_1} + k \frac{q_2}{P_2} \right]$$

$$W = \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^m \frac{q_i q_j}{4\pi\epsilon_0 r_{ij}}$$

$$W_{total} = W_1 + W_2 + W_3 + W_4$$

$$= k \frac{q_1 q_2}{P} + k \frac{q_1 q_3}{P} + k \frac{q_2 q_4}{P} + \dots$$

$$= W = \frac{1}{2} \sum_{i=1}^n q_i V_i$$

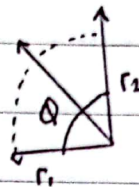
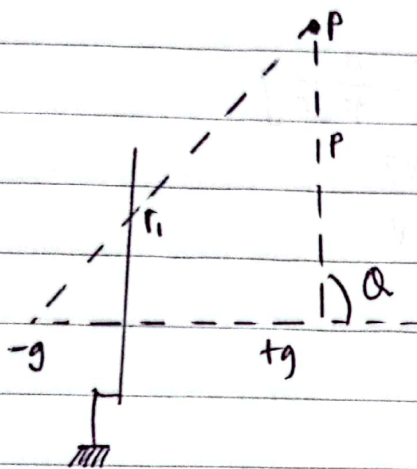
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$$W = \frac{1}{2} \sum_{i=1}^n g_i v_i$$

$$W = \frac{1}{2} \int x v dp$$

$$W = \frac{1}{2} \int \sigma V ds$$

$$W = \frac{1}{2} \int p v dG$$



$$V_1 = \frac{1}{4\pi\epsilon_0} \frac{q}{r} + \frac{-q}{4\pi\epsilon_0 r_1}$$

$$V_1 = \frac{q}{4\pi\epsilon_0} \left[\frac{1}{r} - \frac{1}{r_1} \right]$$

$$\theta = (p^2 + 4h^2 + 4hr \cos \theta)^{1/2}$$

$$\vec{E} = \frac{dV}{dp} = k \left[\frac{1}{r} - \frac{1}{r^2 + 4h^2 + 4hr \cos \theta} \right]$$

$$E_r = \frac{\partial V}{\partial r} = \frac{1}{4\pi\epsilon_0} \left[\frac{1}{r^2} - \frac{r + 2h \cos \theta}{r^3} \right]$$

$$E_\theta = \frac{1}{r} \frac{\partial V}{\partial \theta} = \frac{q}{4\pi\epsilon_0} \left[\frac{2h \cos \theta}{r^3} \right]$$

$$E_z = E_r \cos \theta - E_\theta \sin \theta$$