

Hukum Gauss and Applied

$$\oint_S \vec{E} \cdot d\vec{a} = \int_V (\nabla \cdot \vec{E}) dG \quad \epsilon_0 = \epsilon$$

$$\oint \vec{E} \cdot d\vec{a} = \oint \frac{q}{4\pi\epsilon_0 r^2} r^2 \sin\theta d\theta d\phi$$

$$= \frac{q}{4\pi\epsilon_0} \int_0^\pi \int_0^{2\pi} \sin\theta d\theta d\phi$$

$$= \frac{4\pi q}{4\pi\epsilon_0}$$

$$\oint_S \vec{E} da = \frac{q}{\epsilon_0} \longrightarrow \text{Persamaan gauss dalam bentuk diferensial.}$$

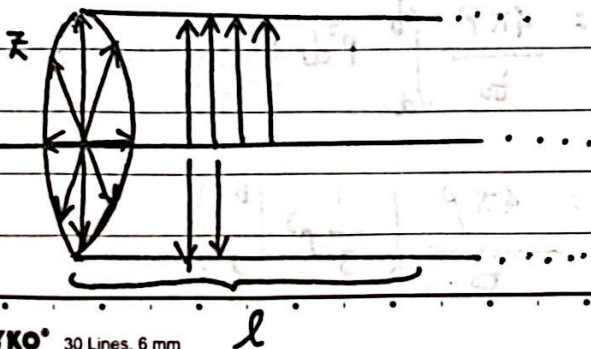
$$\int_V (\nabla \cdot \vec{E}) d\tau$$

$$Q = \int d\tau \quad \oint_S \vec{E} \cdot d\vec{a} = \int_V (\nabla \cdot \vec{E}) d\tau$$

$$\int_V (\nabla \cdot \vec{E}) d\tau = \frac{Q}{\epsilon_0} \longrightarrow \int d\tau$$

$$\frac{1}{\epsilon_0} \int \rho d\tau$$

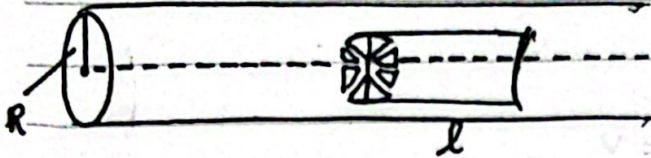
$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} \longrightarrow \text{Hukum gauss dalam bentuk diferensial.}$$



$$\oint \vec{E} da = \frac{q}{\epsilon_0}$$

$$\vec{E} \cdot (2\pi r l) = \frac{\lambda \cdot l}{\epsilon_0}$$

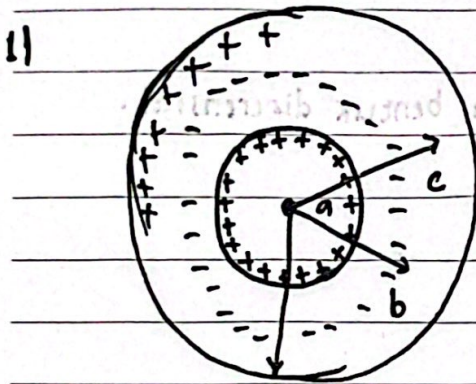
$$\vec{E} = \frac{\lambda}{2\pi\epsilon_0 r} \hat{r}$$



$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E} (2\pi r \cdot l) = \frac{Q}{\epsilon_0}$$

$$\vec{E} = \frac{Q}{2\pi \epsilon_0 r l} \hat{r}_0$$



$$a) \vec{E} = 0$$

$$b) \oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a}$$

$$\vec{E} \cdot (4\pi r^2) = \frac{1}{\epsilon_0} \iiint \rho d\tau$$

$$= \frac{1}{\epsilon_0} \int_0^R \int_0^{2\pi} \int_0^\pi r^2 \sin \theta d\theta d\phi dr$$

$$= \frac{4\pi \rho}{\epsilon_0} r^2 dr$$

$$2) \oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E} (2\pi \cdot \rho \cdot l) = \frac{1}{\epsilon_0} \int_0^R \int_0^\pi$$

$r > b$

$$\oint \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} \iiint \rho d\tau$$

$$= \frac{1}{\epsilon_0} \iiint \rho r^2 \sin \theta d\theta d\phi dr$$

$$= \frac{4\pi \rho}{\epsilon_0} \int_a^b r^2 dr$$

$$= \frac{4\pi \rho}{\epsilon_0} \left(\frac{1}{3} r^3 \Big|_a^b \right)$$