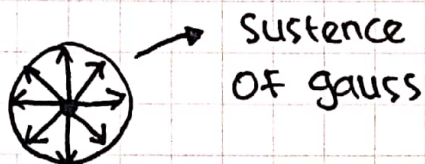


HUKUM GAUSS AND APPLIED

$$\oint_S \vec{E} \cdot d\vec{a} = \oint_V (\nabla \cdot \vec{E}) d\tau$$

$$\tau \Rightarrow V$$



$$\oint \vec{E} \cdot d\vec{a} = \oint \frac{q}{4\pi\epsilon_0 r^2} \sin\theta \, d\theta \, d\phi$$

$$= \frac{q}{4\pi\epsilon_0} \int_0^\pi \int_0^\pi \sin\theta \, d\theta \, d\phi$$

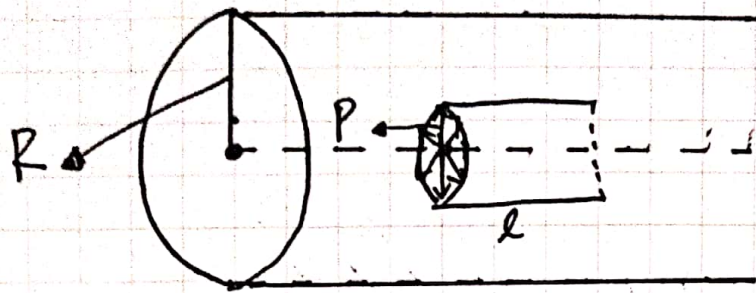
$$= \frac{4\pi q}{4\pi\epsilon_0}$$

$$\oint_S \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0} \rightarrow \text{Persamaan gauss dalam bentuk deferensial}$$

$$\int_V (\nabla \cdot \vec{E}) d\tau$$

$$Q = \rho d\tau$$

$$\oint_S \vec{E} \cdot d\vec{a} = \int_V (\nabla \cdot \vec{E}) d\tau$$



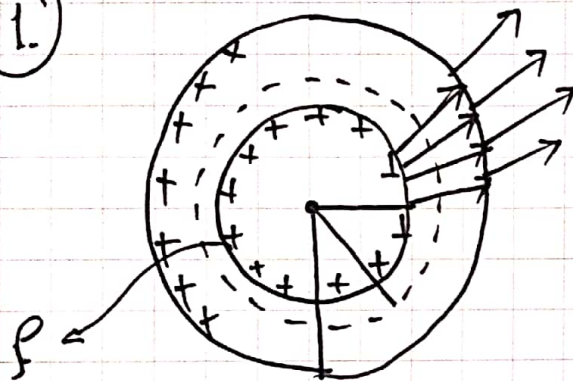
$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E} (2\pi r \cdot l) = \frac{Q}{\epsilon_0}$$

$$\vec{E} = \frac{Q}{2\pi\epsilon_0 r l} \hat{r}_0$$

"Soal"

1.



Hitung $\vec{E}$

1. $r < a$

2. $a < r < b$

3. $r > b$

1. $\vec{E} = 0$

2. $\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$

$$\oint \vec{E} \cdot d\vec{a}$$

$$\vec{E} = (4\pi r^2) = \frac{1}{\epsilon_0} \iiint \rho d\tau$$

$$= \frac{1}{\epsilon_0} \iiint \rho \sin \theta d\theta d\phi dr$$

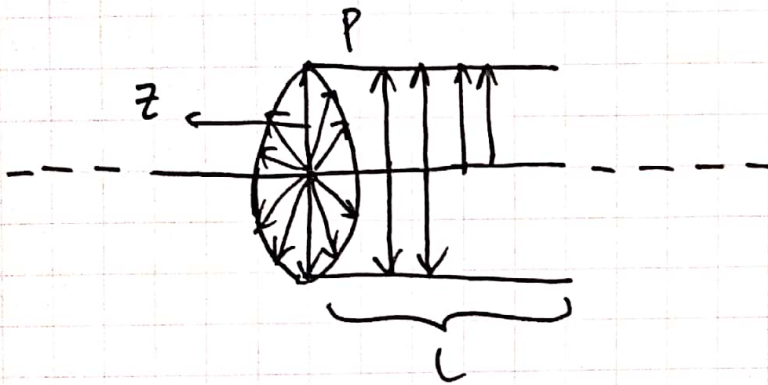
$$= \frac{4\pi\rho}{\epsilon_0} \int_0^a r^2 dr$$

$$\int_0^\pi \int_0^{2\pi} \sin \theta d\theta d\phi = 4\pi$$

$$\int_V (\nabla \cdot \vec{E}) d\tau = \frac{Q}{\epsilon_0} \rightarrow \rho d\tau$$

$$\rightarrow = \frac{1}{\epsilon_0} \int_V \rho d\tau$$

$$\boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon}}$$



$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E} \cdot (2\pi r \cdot L) = \frac{\lambda \cdot L}{\epsilon_0}$$

$$\vec{E} = \frac{\lambda}{2\pi \epsilon_0 r} \hat{r}_0$$

$$\int_0^\pi \int_0^{2\pi} \sin \theta d\theta d\phi = 4\pi$$

↗ Lanjutan disebalik

$$= \frac{4\pi\rho}{\epsilon_0} \left(\frac{1}{3} r^3 \Big|_0^a \right)$$

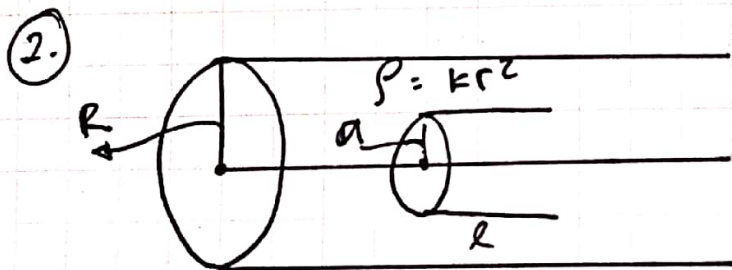
≠ $r > b$

$$\oint \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} \iiint \rho d\tau$$

$$= \frac{1}{\epsilon_0} \iiint \rho r^2 \sin \theta d\theta d\phi dr$$

$$= \frac{4\pi\rho}{\epsilon_0} \int_a^b r^2 dr$$

$$= \frac{4\pi\rho}{\epsilon_0} \left(\frac{1}{3} r^3 \Big|_a^b \right)$$



1.) $r < R$

2.) $r > R$

1.

$$\oint \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} \iiint \rho d\tau$$

$$\vec{E}(2\pi r \cdot l) = \frac{1}{\epsilon_0} \iiint (kr^2) r^2 \sin \theta d\theta d\phi dr \cdot l$$

$$= \frac{k(4\pi)}{\epsilon_0} \int_0^a r^4 dr \rightarrow = \frac{2\pi k}{\epsilon_0} \int_0^R dz \int_0^R r^2 dr$$