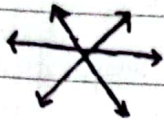


Hukum Gauss

$$\Delta v \neq dv$$

$$\oint_S \vec{E} \cdot d\vec{l} = \int_V (\nabla \cdot \vec{E}) d.G$$



$$\oint \vec{E} \cdot d\vec{a} = \oint \frac{q}{4\pi(2r)} \sin \theta d\phi$$

$$= \frac{q}{4\pi(2r)} \int_0^\pi \int_0^{2\pi} \sin \theta d\theta d\phi$$

$$= \frac{q(2\pi)}{4\pi 60} \int_0^\pi \sin \theta d\theta$$

$$\oint \vec{E} \cdot d\vec{l} = \frac{q}{4\pi\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

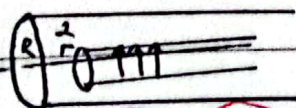
$$\int_V (\nabla \cdot \vec{E}) d.G$$

$$\left. \begin{array}{l} Q_{\text{terp}} = \rho dG \\ Q d\epsilon \\ \lambda dp \end{array} \right\}$$

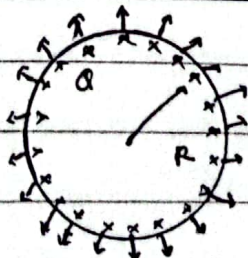
$$\iiint \nabla \cdot \vec{E} \cdot dG = \iiint \frac{\rho dG}{\epsilon_0}$$

$$\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$



$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \vec{r}_0$$

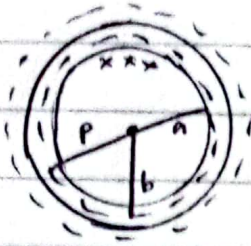


$$\oint \vec{E} \cdot d\vec{a} = \frac{q_{\text{enc}}}{\epsilon_0}$$

$$\vec{E}(4\pi r^2) = \frac{q_{\text{enc}}}{\epsilon_0}$$

Hitung pada a). $P < R$

b). $P > R$



$$\vec{E}(4\pi r^2) = \frac{4\pi}{\epsilon_0} \int_0^a \rho^2 d\rho$$

$$= \frac{4\pi}{\epsilon_0} \left(\frac{1}{3} \rho^3 \right)_0^a$$

$$\vec{E}(4\pi r^2) = \frac{4}{3} \frac{\pi \cdot a^3}{\epsilon_0} = \vec{E} = \frac{4\pi a^3}{3\epsilon_0 r^2} \hat{r}$$

$$r < a \rightarrow \vec{E} = 0$$

$$a < r < b$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E}(4\pi r^2) = \frac{1}{\epsilon_0} \iiint \rho dV$$

$$= \frac{\rho}{\epsilon_0} \int_0^a \int_0^\pi \int_0^{2\pi} \rho^2 \sin\theta d\theta d\phi dr$$

$$= \frac{1}{\epsilon_0} \int_0^a r^2 dr$$

$$\int_0^\pi \int_0^{2\pi} \sin\theta d\theta d\phi = 4\pi$$

$$\vec{E} \rightarrow r > b$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E}(4\pi r^2) = \frac{1}{\epsilon_0} \int_a^b \int_0^\pi \int_0^{2\pi} \rho \sin\theta d\theta d\phi dr$$

$$r > b$$