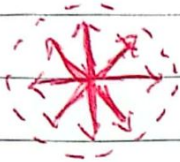


Kuliahman

$$\Delta V \neq dV$$

$$\oint \vec{E} \cdot d\vec{a} = \int (\nabla \cdot \vec{E}) d\tau$$



$$\oint \vec{E} \cdot d\vec{a} = \oint \frac{q}{4\pi\epsilon_0 r^2} r^2 \sin\theta d\theta d\phi$$

$$= \frac{q}{4\pi\epsilon_0} \int_0^\pi \int_0^{2\pi} \sin\theta d\theta d\phi$$

$$= \frac{q(2\pi)}{4\pi\epsilon_0} \int_0^\pi \sin\theta d\theta \quad \begin{matrix} \text{---} -\cos\pi - (-\cos\theta) \\ 1 + 1 = 2 \end{matrix}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

$$\int (\nabla \cdot \vec{E}) d\tau$$

$$\left. \begin{aligned} Q_{inc} &= \rho d\tau \\ &= \sigma da \\ &= \lambda d\phi \end{aligned} \right\}$$

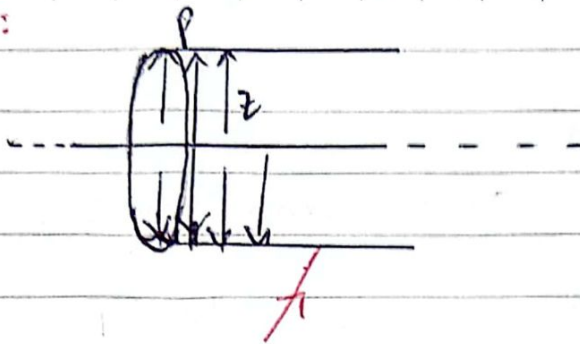
$$\iiint \nabla \cdot \vec{E} d\tau = \iiint \frac{\rho d\tau}{\epsilon_0}$$

$$\boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}}$$

↓

Peramaan Gauss dalam bentuk differensial

Contoh:



Permukaan Gauss

Sehingga,

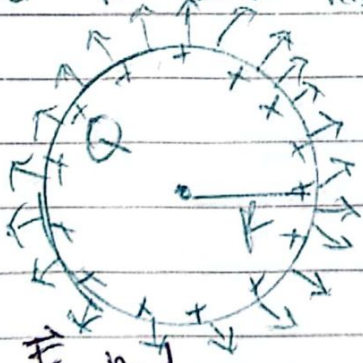
$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0} \quad \lambda \cdot l \quad \vec{E} \cdot (2\pi r \cdot l) = \frac{\lambda l}{\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{\lambda l}{\epsilon_0}$$

$$\vec{E} = \frac{\lambda}{2\pi \epsilon_0 r} \hat{r}_0$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

Fluks yang muncul pada permukaan tertutup karena ada sumber muatan disebut hukum Gauss

Hitung $\vec{E}$ padaa) $r < R$ b) $r > R$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q_r}{\epsilon_0}$$

$$\vec{E} (4\pi r^2) = \frac{Q}{\epsilon_0}$$

$$\vec{E} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{r}_0$$

Kalisma



$$\int_0^\pi \int_0^{2\pi} \sin \theta \, d\theta \, d\phi = 4\pi$$

$$r < a \rightarrow \vec{E} = 0$$

$$a < r < b$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$E(4\pi r^2) = \frac{1}{\epsilon_0} \iiint \rho \, d\tau$$

$$= \frac{1}{\epsilon_0} \int_0^a \int_0^\pi \int_0^{2\pi} r^2 \sin \theta \, d\theta \, d\phi \, dr$$

$$= \frac{4\pi}{\epsilon_0} \int_0^a r^2 \, dr$$

$$\vec{E}(4\pi r^2) = \frac{4\pi}{\epsilon_0} \int_0^a r^2 \, dr$$

$$= \frac{4\pi}{\epsilon_0} \left(\frac{1}{3} r^3 \right) \Big|_0^a$$

$$\vec{E}(4\pi r^2) = \frac{4}{3} \pi \frac{r^3}{\epsilon_0} = \vec{E} = \frac{r a^3}{3 \epsilon_0 r^2} \hat{r}_0$$

$$\vec{E} \rightarrow r > b$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E} \cdot (4\pi r^2) = \frac{1}{\epsilon_0} \iiint_{a=0}^b \int_{\theta=0}^{\pi} \int_{\phi=0}^{2\pi} \rho r^2 \sin \theta \, d\theta \, d\phi \, dr$$

$$r > b$$

$$\vec{E} (4\pi r^2) = \frac{\rho}{\epsilon_0} 4\pi \int_a^b r^2 \, dr$$

$$= \frac{\rho 4\pi}{\epsilon_0} \left(\frac{1}{3} r^3 \right) \Big|_a^b$$

$$= \frac{\rho 4\pi}{3\epsilon_0} (b^3 - a^3)$$

$$\vec{E} = \frac{\rho}{3\epsilon_0 r^2} (b^3 - a^3)$$