

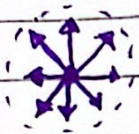
kalisma

Hukum Gauss

$$\Delta v \neq dv$$

$$\oint \vec{E} \cdot d\vec{q} = \int (\nabla \cdot \vec{E}) d\tau$$

menentukan lipat 2 atau 1



$$\oint \vec{E} \cdot d\vec{a} = \oint \frac{q}{4\pi\epsilon_0 r^2} r^2 \sin \theta d\theta d\phi$$

$$= \frac{q}{4\pi\epsilon_0} \int_0^\pi \int_0^{2\pi} \sin \theta d\theta d\phi$$

→ $-\cos \theta \Big|_0^\pi = -(\cos \pi - \cos 0) = -(-1 - 1) = 2$

$$= \frac{q (2\pi)}{4\pi\epsilon_0} \int_0^\pi \sin \theta d\theta$$

$$= \frac{q (2\pi)}{4\pi\epsilon_0} \cdot 2$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0} //$$

$$\int_V (\nabla \cdot \vec{E}) d\tau$$

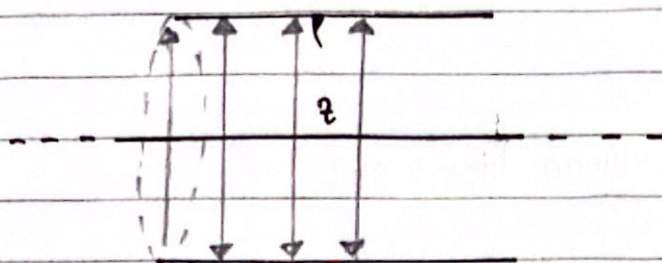
$$\left. \begin{aligned} Q_{inc} &= \rho d\tau \\ &= \sigma da \\ &= \lambda dl \end{aligned} \right\}$$

$$\boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}}$$

Persamaan Gauss dalam bentuk differensial

$$\iiint \nabla \cdot \vec{E} d\tau = \iiint \frac{\rho}{\epsilon_0} d\tau$$

Contoh :



Permutasi Gauss

$$\oint \vec{E} \cdot d\vec{a} = \frac{q_{in}}{\epsilon_0} = \lambda \cdot l$$

$$\oint \vec{E} \cdot (d\vec{a}) = \frac{\lambda l}{\epsilon_0}$$

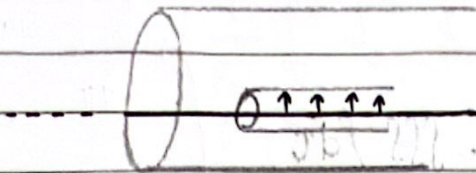
$$\vec{E} (2\pi r \cdot l) = \frac{\lambda l}{\epsilon_0}$$

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$$\boxed{\vec{E} = \frac{\lambda}{2\pi \epsilon_0} \hat{r}}$$

Fluks yang muncul pada luasan tertutup karena ada sumber muatan disebut hukum Gauss.

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

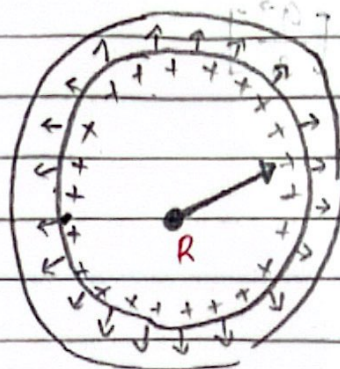


$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r}_0$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0}$$

$$\vec{E} (2\pi r \ell) = \frac{Q}{\epsilon_0}$$

$$\vec{E} = \frac{Q}{2\pi\epsilon_0 r} \hat{r}_0, \text{ dimana } r < R$$



$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0}$$

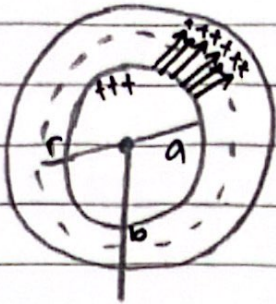
$$\vec{E} (4\pi r^2) = \frac{q}{\epsilon_0}$$

$$E = \frac{q}{4\pi\epsilon_0 r^2} \hat{r}_0, \text{ dimana } r < R$$

Hitung

$$1. r < R$$

$$2. r > R$$



$$r < a \rightarrow \vec{E} \cdot \vec{0}$$

$$a < r < b$$

$$\oint \vec{E} \cdot d\vec{q} = \frac{Q}{\epsilon_0}$$

$$\vec{E} (4\pi r^2) = \frac{1}{\epsilon_0} \iiint \rho d\tau$$

$$\frac{\rho}{\epsilon_0} \int_0^a \int_0^\pi \int_0^{2\pi} r^2 \sin\theta \, d\theta \, d\phi \, d\tau$$

$$= \frac{4\pi}{\epsilon_0} \int_0^a r^2 \rho \, dr$$

$$= \frac{4\pi}{\epsilon_0} \left[\frac{1}{3} r^3 \right]_0^a$$

$$= \frac{4\pi}{\epsilon_0} \left[\frac{1}{3} (a^3) - \frac{1}{3} (0)^3 \right]$$

$$= \frac{4\pi}{\epsilon_0} \left[\frac{a^3}{3} \right]$$

$$\vec{E} (4\pi r^2) = \frac{4\pi a^3}{3\epsilon_0}$$

$$\vec{E} = \frac{\rho a^3}{3\epsilon_0 r^2}$$

$$\vec{E} = \frac{\rho a^3}{3\epsilon_0 r^2}$$

$$\vec{E} \rightarrow r > b$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$E(4\pi r^2) = \frac{1}{\epsilon_0} \int_a^b \int_0^{2\pi} \int_0^\pi \rho \sin \theta \, d\theta \, d\phi \, dr$$

$$= \frac{\rho}{\epsilon_0} \int_a^b \left[\int_0^{2\pi} \int_0^\pi \sin \theta \, d\theta \, d\phi \right] dr \rightarrow \text{hasilnya } 4\pi$$

$$= \frac{4\pi\rho}{\epsilon_0} \int_a^b r^2 \, dr$$

$$= \frac{4\pi\rho}{\epsilon_0} \left[\frac{1}{3} r^3 \Big|_a^b \right]$$

$$\vec{E}(4\pi r^2) = \frac{4\pi\rho}{3\epsilon_0} (b^3 - a^3)$$

$$= \frac{\rho}{3\epsilon_0 r^2} (b^3 - a^3) //$$