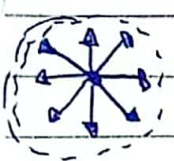


Hukum Gauss

$$\Delta v \neq \Delta v$$

$$\oint \vec{E} \cdot d\vec{a} = \int (\nabla \cdot \vec{E}) d\tau \quad \text{menentukan lipat 2 atau 1}$$



$$\oint \vec{E} \cdot d\vec{a} = \oint \frac{q}{4\pi\epsilon_0 r^2} r^2 \sin\theta d\theta d\phi$$

$$= \frac{q}{4\pi\epsilon_0} \int_0^\pi \int_0^{2\pi} \sin\theta d\theta d\phi = \frac{q}{4\pi\epsilon_0} [-\cos\theta]_0^\pi = \frac{q}{4\pi\epsilon_0} (1 + 1) = \frac{2q}{4\pi\epsilon_0}$$

$$= \frac{q(2\pi)}{4\pi\epsilon_0} \int_0^\pi \sin\theta d\theta = \frac{q(2\pi)}{4\pi\epsilon_0} \cdot 2$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{4\pi q}{4\pi\epsilon_0}$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0} //$$

$$\int (\nabla \cdot \vec{E}) d\tau$$

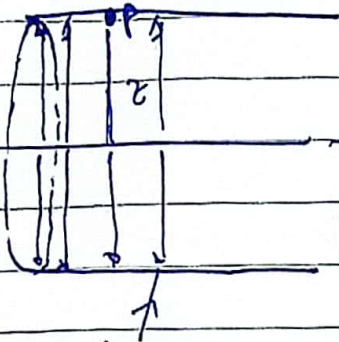
$$\left. \begin{aligned} Q_{enc} &= \rho d\tau \\ &= \sigma da \\ &= \lambda dl \end{aligned} \right\}$$

$$\boxed{\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0}}$$

~ persamaan Gauss dalam bentuk differensial.

$$\iiint \nabla \cdot \vec{E} d\tau = \iiint \frac{\rho d\tau}{\epsilon_0}$$

contoh :



Permukaan Gauss

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0} \cdot \lambda \cdot L$$

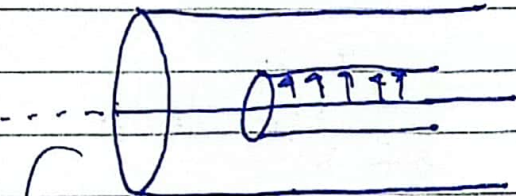
$$\oint \vec{E} (da) = \frac{\lambda L}{\epsilon_0}$$

$$\oint (2\pi r \cdot E) = \frac{\lambda L}{\epsilon_0}$$

$$E = \frac{\lambda}{2\pi \epsilon_0 r}$$

Flux yang muncul pada luasan tertutup karena ada sumber muatan disebut hukum Gauss.

$$\oint \vec{E} \cdot d\vec{a} = \frac{q}{\epsilon_0}$$

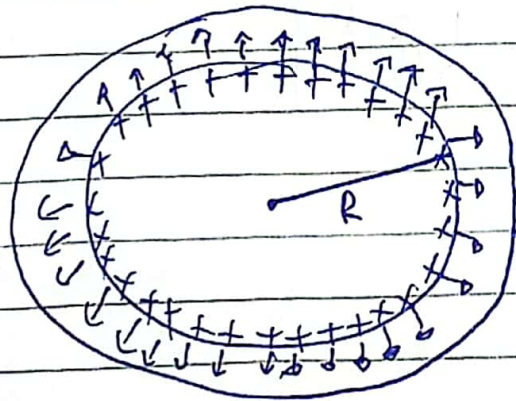


$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r}_0$$

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0}$$

$$\vec{E} (2\pi r l) = \frac{Q}{\epsilon_0}$$

$$\vec{E} = \frac{Q}{2\pi\epsilon_0 r l} \hat{r}_0, \text{ dimana } r < R$$



$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0}$$

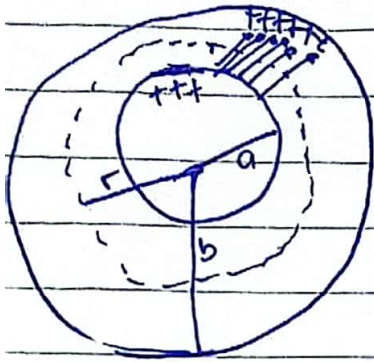
$$\vec{E} (4\pi r^2) = \frac{Q}{\epsilon_0}$$

$$\vec{E} = \frac{Q}{4\pi\epsilon_0 r^2} \hat{r}_0, \text{ dimana } r < R$$

Hitung E pada

1. $r < R$

2. $r > R$



$$r < a \rightarrow \vec{E} = 0$$

$$a < r < b$$

$$\oint \vec{E} \cdot d\vec{q} = \frac{Q}{\epsilon_0}$$

$$\int_0^\pi \int_0^{2\pi} \sin\theta d\theta d\phi = 4\pi$$

$$\vec{E}(4\pi r^2) = \frac{1}{\epsilon_0} \iiint \rho d\tau$$

$$= \frac{\rho}{\epsilon_0} \int_0^a \int_0^\pi \int_0^{2\pi} r^2 \sin\theta d\theta d\phi dr$$

$$= \frac{4\pi}{\epsilon_0} \int_0^a r^2 dr$$

$$= \frac{4\pi}{\epsilon_0} \left[\frac{1}{3} r^3 \right]_0^a$$

$$= \frac{4\pi}{\epsilon_0} \left[\frac{1}{3} (a^3) - \frac{1}{3} (0)^3 \right]$$

$$= \frac{4\pi}{\epsilon_0} \left[\frac{a^3}{3} \right]$$

$$\vec{E}(4\pi r^2) = \frac{4\pi a^3}{3\epsilon_0}$$

$$\vec{E} = \frac{\rho a^3}{3\epsilon_0 r^2}$$

$$\vec{E} = \frac{\rho a^3}{3\epsilon_0 r^2}$$

$$\vec{E} \rightarrow r > b$$

$$\oint \vec{E} \cdot d\vec{a} = \frac{Q}{\epsilon_0}$$

$$\vec{E} (4\pi r^2) = \frac{1}{\epsilon_0} \int_a^b \int_0^{2\pi} \int_0^\pi \rho \sin\theta \, d\theta \, d\phi \, dr$$

$$= \frac{\rho}{\epsilon_0} \int_a^b \left[\int_0^{2\pi} \int_0^\pi \sin\theta \, d\theta \, d\phi \right] dr$$

hasilnya 4π

$$= \frac{4\pi \rho}{\epsilon_0} \int_a^b r^2 \, dr$$

$$= \frac{4\pi \rho}{\epsilon_0} \left[\frac{1}{3} r^3 \right]_a^b$$

$$\vec{E} (4\pi r^2) = \frac{4\pi \rho}{3\epsilon_0} (b^3 - a^3)$$

$$= \frac{\rho}{3\epsilon_0 r^2} (b^3 - a^3) //$$