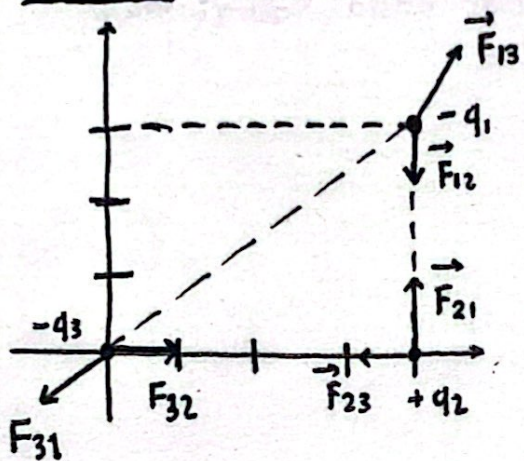


Kalisma



$$\vec{F}_{12} = K \frac{q_1 q_2}{3^2} \left(\frac{0\hat{i} + 3\hat{j}}{3} \right)$$

$$\vec{F}_{12} = -K \frac{q_1 q_2}{3^2} \hat{j}$$

$$\vec{F}_{13} = K \frac{q_1 q_3}{5^2} \left(\frac{4\hat{i} + 3\hat{j}}{5} \right)$$

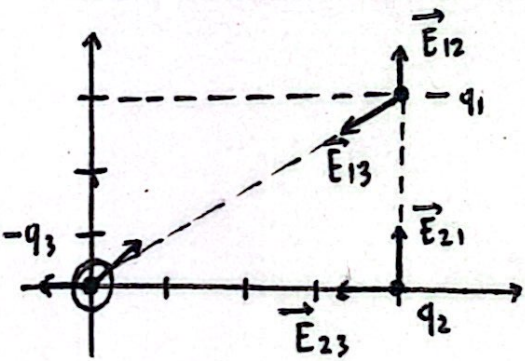
$$\vec{F}_{31} = \frac{1}{4\pi\epsilon_0} \frac{q_3 q_1}{5^2} \left(\frac{-4\hat{i} - 3\hat{j}}{5} \right)$$

$$\vec{F}_{32} = \frac{1}{4\pi\epsilon_0} \frac{q_3 q_2}{4^2} \hat{i}$$

$$\vec{F}_{21} = K \frac{q_2 q_1}{3^2} (-\hat{j})$$

$$\vec{F}_{23} = K \frac{q_2 q_3}{4^2} (-\hat{i})$$

• Mencari medan (arah medan)



- negatif : menuju ke arah titik (mendekati)
- positif : menjauhi

$$\vec{E}_{32} = \frac{F}{q_3} = K \frac{q_3 q_2 / r^2}{q_3} = K \frac{q_2}{r^2}$$

$$\vec{E}_{32} = K \frac{q_2}{4^2} (-\hat{i})$$

$$\vec{E}_{31} = K \frac{q}{5^2} \left(\frac{4\hat{i} + 3\hat{j}}{5} \right)$$

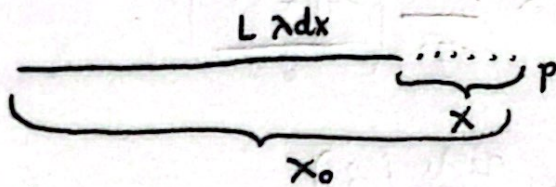
Muatan Diskrit

$$1) E = K \frac{q}{r^2} \hat{r}_0 = K \sum_{i=1}^n \frac{q_i}{r_i^2} \hat{r}_{0i} = K \left[\sum_{i=1}^n \frac{q_i}{r_i^2} \hat{r}_{0i} + \frac{q_2}{r_2^2} \hat{r}_{02} + \dots + \frac{q_n}{r_n^2} \hat{r}_{0n} \right]$$

$$2) \vec{E} = K \int \frac{dq}{r^2} \hat{r}_0 = K \int \frac{\lambda dx}{r^2} \hat{r}_0 \rightarrow \text{medan pada kawat jalur}$$

$$3) \text{ [Diagram of a rectangular area with diagonal lines] } \vec{E} = K \iint \frac{\sigma dq}{r^2} \hat{r}_0 \rightarrow \text{luas}$$

$$4) \text{ [Diagram of a sphere] } \vec{E} = K \iiint \frac{\rho dr}{r^2} \hat{r}_0 \rightarrow \text{volume}$$



$$\vec{E}_p = ?$$

$$\vec{E} = K \int_0^L \frac{\lambda dx}{(x_0 - x)^2} = K \lambda \int_0^L \frac{dx}{(x_0 - x)^2}$$

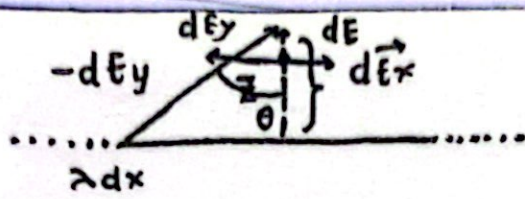
$$\begin{aligned} \int \frac{dx}{x^2} &= \int_0^L x^{-2} dx \\ &= x^{-1} \Big|_0^L \\ &= \frac{1}{x} \Big|_0^L \end{aligned}$$

$$= K \lambda \int_0^L (x_0 - x)^{-2} dx$$

$$= K \lambda \left[\frac{1}{(x_0 - x)} \Big|_0^L \right]$$

$$= K \lambda \left[\frac{1}{(x_0 - L)} - \frac{1}{(x_0 - 0)} \right] L$$

$$= K \lambda \left[\frac{x_0 - (x_0 - L)}{x_0 (x_0 - L)} \right] = K \lambda \frac{L}{x_0 (x_0 - L)}$$



$$\vec{dE} = d\vec{E}_y + d\vec{E}_x$$

$$d\vec{E} = d\vec{E}_y$$

$$dE_y = dE \cos \theta$$

$$\vec{E} = K \int_{-\infty}^{\infty} \frac{\lambda dx}{r^2} \cos \theta$$

$$dq = \lambda dx$$

Misal :

$$\cos \theta = \frac{z}{r}$$

$$r = \frac{z}{\cos \theta}$$

$$\tan \theta = \frac{x}{z}$$

$$x = z \tan \theta$$

$$x = -\infty$$

$$\theta = -\frac{\pi}{2}$$

$$x = \infty$$

$$\theta = \frac{\pi}{2}$$