

► Ringkasan Part 4 (upload) Mat. Caya

1. Koordinat Cartesius (x, y, z)

$$d\vec{r} = \hat{i} dx + \hat{j} dy + \hat{k} dz$$

$$d\tau = dx dy dz$$

$$\text{- gradien : } \nabla t = \hat{i} \frac{\partial t}{\partial x} + \hat{j} \frac{\partial t}{\partial y} + \hat{k} \frac{\partial t}{\partial z}$$

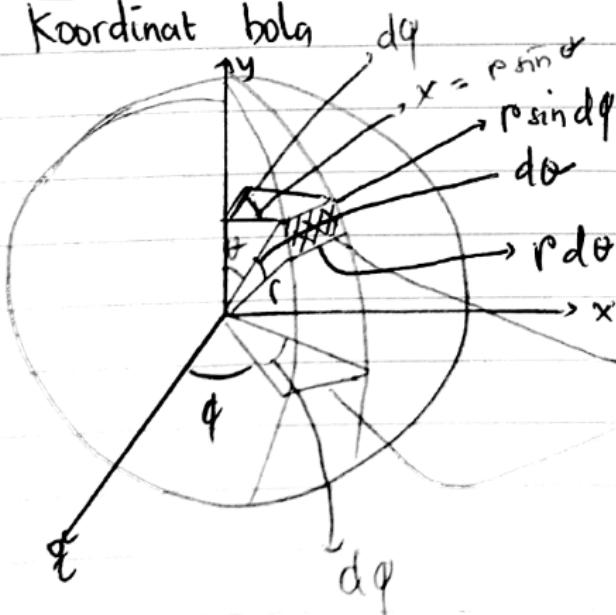
$$\text{- Divergensi : } \nabla \cdot \vec{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$$

$$\text{- Rotasi : } \nabla \times \vec{v} = \hat{i} \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) + \hat{j} \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) + \hat{k} \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right)$$

$$\begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_x & v_y & v_z \end{vmatrix}$$

Sistem koordinat:

2. Koordinat bola



$$\begin{vmatrix} \sin \theta = \frac{x}{r} \\ x = r \sin \theta \end{vmatrix}$$

$$\begin{aligned} d\tau &= dp \times d\theta \times d\phi \\ &= r d\theta r \sin \theta d\phi \\ &= r^2 \sin \theta d\theta d\phi \end{aligned}$$

$$\begin{aligned} d\vec{r} &= dp \cdot d\theta \cdot d\phi \\ &= r^2 \sin \theta d\theta d\phi dp \end{aligned}$$

$$\nabla T = \hat{i} \frac{\partial T}{\partial x} + \hat{j} \frac{\partial T}{\partial y} + \hat{k} \frac{\partial T}{\partial z}$$

$$\nabla T = \frac{\partial T}{\partial \rho} \hat{\rho} + \frac{1}{\rho} \frac{\partial T}{\partial \theta} \hat{\theta} + \frac{1}{\rho \sin \theta} \frac{\partial T}{\partial \phi} \hat{\phi}$$

$$\nabla \cdot T =$$

$$\nabla \propto T :$$

$$\begin{aligned} A &= \int_0^{2\pi} \int_0^{\pi} r^2 \sin \theta \, d\theta \, d\phi \\ &= r^2 \int_0^{2\pi} d\phi \int_0^{\pi} \sin \theta \, d\theta \\ &= 2\pi r^2 \int_0^{\pi} \sin \theta \, d\theta \\ &= 2\pi \left[-\cos \theta \right]_0^{\pi} \\ &= \underline{\underline{4\pi r^2}} \end{aligned}$$

$$V = \int_0^{\pi} \int_0^{\pi} \int_0^{\rho} r^2 \sin \theta \, dr \, d\phi \, d\theta$$

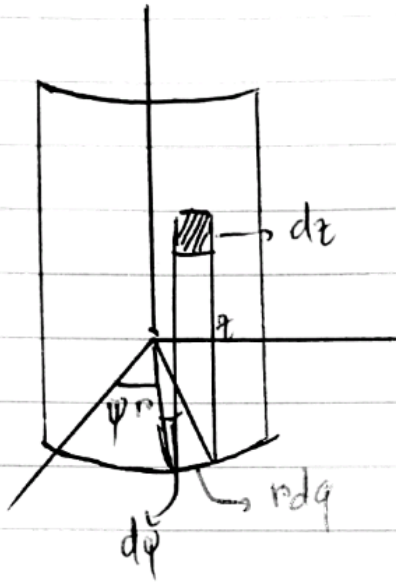
$$= \left(\int_0^{\pi} \sin \theta \, d\theta \right) \int_0^{2\pi} d\phi \int_0^{\rho} r^2 \, dr$$

$$= 2 (2\pi) \int_0^{\rho} r^2 \, dr$$

$$= 4\pi \left(\frac{1}{3} \rho^3 \right) = \underline{\underline{\frac{4}{3} \pi \rho^3}}$$

$$\begin{aligned} & \left[-\cos \theta \right]_0^{\pi} \\ &= -[\cos \pi - \cos 0] \\ &= -[-1 - 1] \\ &= -(-2) \\ &= 2 \end{aligned}$$

3. Koordinat silinder



$$dA = dr \times dz \\ = r dq$$

$$dV = r dq dz dr$$

► Listrik Statis → foto kopi, TV tabung, print

• Gaya Coulomb

• Medan listrik

• distrit

• Non distrit

• Potensial

• Distrit

• non Distrit

• Usaha dan energi

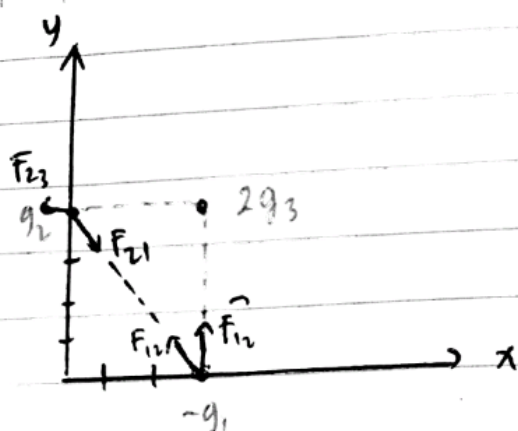
atom memiliki kelengkapan elektron.

atom kelebihan elektron.



$$Q = \pm Ne$$

$$\vec{F} = \frac{1}{4\pi\epsilon_0} \frac{Qq}{r^2}$$



$$k = \frac{1}{4\pi\epsilon_0}$$

$$p_c = \frac{\vec{r}}{|\vec{r}|}$$

$$\sqrt{3^2 + 4^2} = \sqrt{25} = 5$$

$$\vec{F}_{q_1} =$$

$$\vec{F}_{12} = k \frac{q_1 (2q_3)}{4^2} \hat{j}$$

$$\vec{F}_{12} = k \frac{2q_1 q_2}{5^2} \left(\frac{-3\hat{i} + 4\hat{j}}{5} \right)$$

$$\vec{F}_{12} = \frac{-3k q_1 q_2}{125} \hat{i} + \frac{4k q_1 q_2}{125} \hat{j}$$

$$\vec{F}_{\text{total}} = \frac{3k q_1 q_3}{125} \hat{i} + \left(\frac{2k q_1 q_3}{16} + \frac{4k q_1 q_2}{125} \right) \hat{j}$$

$$\vec{F}_{21} = k \frac{q_2 q_1}{5^2} \left(\frac{3\hat{i} - 4\hat{j}}{5} \right)$$

$$= \frac{3k q_2 q_1}{125} \hat{i} + \frac{4k q_2 q_1}{125} \hat{j}$$

$$\vec{F}_{23} = -k \frac{q_2 q_3}{3^2} \hat{i}$$

$$= -2k \frac{q_2 q_3}{9} \hat{i}$$