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Pendidikan fisika 20B

METODA PENENTUAN POTENSIAL

3.1 Persamaan Laplace

$\oint \vec{E} \cdot d\vec{e} = 0$, untuk $\vec{E}$ konservatif

$$\oint \vec{E} \cdot d\vec{p} = \int \nabla \cdot \vec{E} \cdot dA = 0$$

$$\nabla \cdot \vec{E} = 0$$

$$\nabla E = \frac{\rho}{\epsilon}$$

$$E = -\nabla V$$

$$\nabla \vec{E} = -\nabla \cdot \nabla V$$

$$\frac{1}{\epsilon_0} \rho = -\nabla^2 V$$

$$\nabla^2 V = -\frac{1}{\epsilon_0} \rho \quad (\text{Hukum Poisson})$$

$$\nabla^2 V = 0 \quad (\text{Persamaan Laplace})$$

$$\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

$$\frac{\partial^2 V}{\partial x^2} = 0; \quad \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} = 0; \quad \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2} = 0$$

$$\nabla^2 V = \frac{1}{\epsilon_0} \rho$$

Dalam persamaan Laplace $\rho = 0$, $\epsilon_0 = \text{konstan}$

$\nabla^2 V = 0$; untuk satu dimensi, maka

$\frac{\partial^2 V_x}{\partial x^2} = 0$, karena V fungsi dari x saja, maka

$$\frac{d^2 V_x}{dx^2} = \frac{d}{dx} \left(\frac{dV}{dx} \right) = 0$$

$$\frac{dV_x}{dx} = k, \quad k = \text{konstan}$$

$$dV_x = k dx$$

$$V_x = kx + b, \quad b = \text{konstan}$$

$$V(x) = kx + b$$

Untuk koordinat bola, maka persamaan Laplace satu dimensi

$$\nabla^2 V = 0$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) = 0$$

$$r^2 \frac{\partial V}{\partial r} = r^2 \frac{dV}{dr} = k$$

$$dV = \frac{1}{r^2} k dr$$

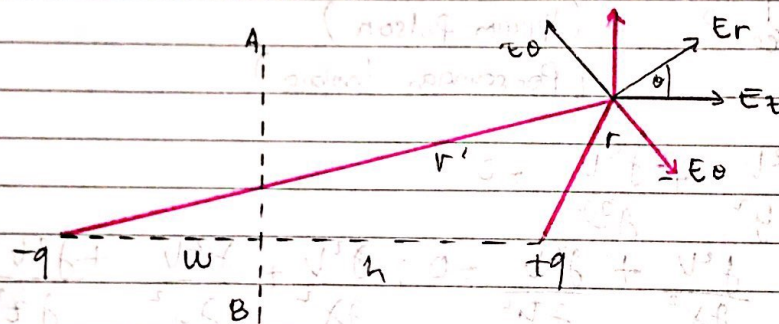
$$V(r) = -\frac{1}{r} k + C$$

3.2 Metoda bayangan

a) Muatan titik dengan batang konduktor

$$\therefore E_p = \frac{q}{4\pi\epsilon_0} \left[\frac{1}{r^2} - \frac{(r+2h\cos\theta)}{(r^2+4h^2+4hr\cos\theta)^{\frac{3}{2}}} \right]$$

$$\therefore E_o = \frac{q}{4\pi\epsilon_0} \left[\frac{2h\sin\theta}{(r^2+4h^2+4hr\cos\theta)^{\frac{3}{2}}} \right]$$



$$E_z = E_r \cos\theta - E_o \sin\theta$$

$$E_z = \frac{q}{4\pi\epsilon_0} \left[\frac{\cos\theta}{r^2} - \frac{r\cos\theta + 2h}{r^3} \right]$$

Untuk setiap titik pada bidang AB, $r - r' = q$, sehingga

$$E_z(q) = \frac{q}{4\pi\epsilon_0} \left[\frac{\cos\theta}{a^2} - \frac{q\cos\theta + 2h}{a^3} \right]$$

$$= -\frac{q}{4\pi\epsilon_0} \left(\frac{2h}{a^3} \right) = -\frac{qh}{2\pi\epsilon_0 a^3} = \frac{1}{\epsilon_0} \sigma(q)$$

$$\sigma(q) = -\frac{qh}{2\pi a^3}$$

σ = muatan induksi persatuan luas pada pelat konduktor AB

Muatan induksi total pada pelat AB:

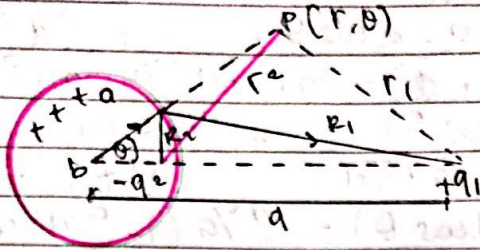
$$\int_0^\infty \sigma dA = \int_0^\infty \sigma (2\pi x dx) = -hq \int_0^\infty \frac{x}{a^3} dx$$

$$= -hq \int_0^\infty \frac{q}{q^3} dq$$

$$= -q \rightarrow \text{bukti sebagai muatan bayangan.}$$

b) Muatan titik dengan bola konduktor

kita menempatkan muatan $-q$ sedemikian rupa sehingga V dipermukaan bola $V=0$



$$V = \frac{q}{4\pi\epsilon_0} \left(\frac{1}{r_1} - \frac{1}{r_2} \right) = 0$$

$$r_1^2 = a^2 + d^2 - 2ad \cos \theta$$

$$r_2^2 = a^2 + b^2 - 2ab \cos \theta$$

untuk $V=0$ maka,

$$\frac{q_1}{r_1} = \frac{q_2}{r_2} \rightarrow \frac{q_1^2}{r_1^2} = \frac{q_2^2}{r_2^2} = \frac{a^2 + d^2 - 2ad \cos \theta}{a^2 + b^2 - 2ab \cos \theta}$$

$$\left(\frac{q_1}{q_2} \right)^2 = \left(\frac{r_1}{r_2} \right)^2 = \frac{d}{b} \left(\frac{a^2/d + d - 2a \cos \theta}{a^2/b + b - 2a \cos \theta} \right)$$

dengan hubungan diatas berlaku untuk setiap θ , bila

$$1) a^2 = ab$$

$$2) \left(\frac{q_1}{q_2} \right) = \frac{d}{b}, \text{ karena } d > b \text{ dan } q_1 > q_2$$

bola konduktor dengan jari-jari a dengan $V=0$, dengan muatan q , sejarak λ dari pusat bola, maka bola tersebut tepat digantungkan dengan muatan titik $(-q)$

$$\frac{q_1^2}{q_2^2} = \frac{d}{b}; -q_2 = \pm \sqrt{\frac{b^2}{d}} \cdot q_1; \text{ untuk } b = \frac{q^2}{d}$$

$$q_2 = -\frac{q}{d} q_1$$

$$\text{Jadi } V(r, \theta) = V_p$$

$$V_p = \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{r_1} - \frac{q_2}{r_2} \right)$$

$$= \frac{1}{4\pi\epsilon_0} \left(\frac{q_1}{r_1} - \frac{a/d}{r_2} \right)$$

$$r_1 = (r^2 + d^2 - 2rd \cos \theta)^{\frac{1}{2}}$$

$$r_2 = (r^2 + b^2 - 2rb \cos \theta)^{\frac{1}{2}}$$

$$V_p = \frac{q_1}{4\pi\epsilon_0} \left(\frac{1}{(r^2 + d^2 - 2rd \cos \theta)^{\frac{1}{2}}} - \frac{a/d}{(r^2 + \frac{a^4}{d^2} - 2r(\frac{a^2}{d}) \cos \theta)^{\frac{1}{2}}} \right)$$

$$f_r = -\frac{\partial v}{\partial r} ; E_\theta = -\frac{1}{r} \frac{\partial v}{\partial \theta}$$

husus untuk permukaan bola : dimana $r = a$

$$E_r = -\frac{q_1}{4\pi\epsilon_0} \left[\frac{-(a - d \cos \theta)}{(a^2 + d^2 - 2ad \cos \theta)^{3/2}} + \frac{a/d (a - \frac{a^2}{d} \cos \theta)}{(a^2 + \frac{a^3}{d^2} - 2a(\frac{a^1}{d}) \cos \theta)^{3/2}} \right. \\ \left. + \frac{a^2/d^3 (1 - a/d \cos \theta)}{(d^2 + a^2 - 2ad \cos \theta)^{3/2}} + \frac{d/a (1 - \frac{a}{d} \cos \theta)}{(a^2 + d^2 - 2ad \cos \theta)^{3/2}} \right]$$

$$E_r = -\frac{q_1}{4\pi\epsilon_0} \left[\frac{-(a - d \cos \theta) + \frac{a^2}{d} (1 - \frac{a}{d} \cos \theta)}{(a^2 + d^2 - 2ad \cos \theta)^{3/2}} \right]$$

$$E_r = \frac{-q_1}{4\pi\epsilon_0 a} \left(\frac{d^2 - a^2}{(a^2 + d^2 - 2ad \cos \theta)^{3/2}} \right)$$

Dengan cara yang sama

$$E_\theta = 0$$

Disini terjadi pergeseran listrik D

$$D = \epsilon_0 E \quad -D = \sigma_f = \sigma$$

$$\sigma = \epsilon_0 E_r$$

$$\sigma = -\frac{q_1}{4\pi a} \left(\frac{d^2 - a^2}{(a^2 + d^2 - 2ad \cos \theta)^{3/2}} \right)$$

σ = muatan induksi permukaan luas pada bola konduktor

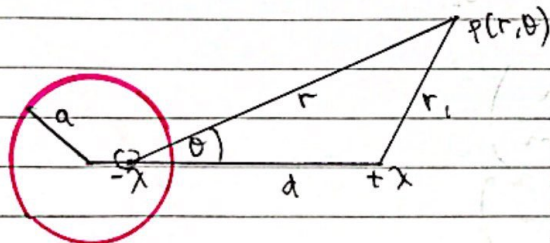
F = gaya antara bola dengan q_1 adalah

$$F = -\frac{1}{4\pi\epsilon_0} \frac{q_1 q_1}{(d-b)^2}$$

$$F = -\frac{1}{4\pi\epsilon_0} \frac{q q_1}{a(d-b)^2}$$

c) Muatan garis dengan silinder bermuatan :

Ada 2 muatan garis saling sejajar terpisah jarak d



Dimana $V=0$

V permukaan $= 0$

$$V_p = \frac{+\lambda}{d\pi\epsilon_0} \ln r' - \frac{\lambda}{2\pi\epsilon_0} \ln r_1$$

agar $V=0$ maka :

$$C = -\frac{\lambda}{4\pi\epsilon_0} \ln \left(\frac{r_1}{r} \right)^2, V, \text{ semua permukaan, dimana :}$$

$$\left(\frac{r_1}{r} \right)^2 = \frac{r^2 + d^2 - 2rd \cos \theta}{r^2} = m^2 = \text{konstanta dengan } 0 < m < \infty$$

$$r^2 + d^2 - 2rd \cos \theta = m^2 r^2 \text{ untuk } x = r \cos \theta, y = r \sin \theta \text{ maka:}$$

$$r^2 + d^2 - 2rd \cos \theta = m^2 r^2$$

diperoleh :

$$\left(x + \frac{q}{m^2 - 1}\right)^2 + y^2 = \frac{m^2 d^2}{(m^2 - 1)^2} \rightarrow \left(\frac{-d}{m^2 - 1}; 0\right)$$

Jari-jari silinder $a = \frac{md}{m^2 - 1}$, $x = \frac{-d}{m^2 - 1}$, $y = 0$

Untuk $m > 1$ letak sumbu silinder dengan harga $v = 0$ adalah pada jarak $\frac{q}{m^2 - 1} = m \cdot a$

dan jarak : $x = \frac{ad}{m^2 - 1} = \frac{a}{m} = \frac{a^2}{r}$

$$x = \frac{\sigma}{p}$$